Reasoning about Knowledge and Beliefs Lecture 12

Eric Pacuit

University of Maryland, College Park

pacuit.org epacuit@umd.edu

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Reasoning about Knowledge and Beliefs

Robert Aumann. Agreeing to Disagree. Annals of Statistics 4 (1976).

Theorem. Suppose that *n* agents share a common prior and have different private information. If there is common knowledge in the group of the posterior probabilities, then the posteriors must be equal.

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S. Morris. *The common prior assumption in economic theory*. Economics and Philosophy, 11, pgs. 227 - 254, 1995.

Generalized Aumann's Theorem

Qualitative versions: *like-minded individuals cannot agree to make different decisions*.

M. Bacharach. Some Extensions of a Claim of Aumann in an Axiomatic Model of Knowledge. Journal of Economic Theory (1985).

J.A.K. Cave. Learning to Agree. Economic Letters (1983).

D. Samet. Agreeing to disagree: The non-probabilistic case. Games and Economic Behavior, Vol. 69, 2010, 169-174.

The Framework

Knowledge Structure: $\langle W, \{\Pi_i\}_{i \in \mathcal{A}} \rangle$ where each Π_i is a partition on W ($\Pi_i(w)$) is the cell in Π_i containing w).

Decision Function: Let *D* be a nonempty set of **decisions**. A decision function for $i \in A$ is a function $\mathbf{d}_i : W \to D$. A vector $\mathbf{d} = (d_1, \ldots, d_n)$ is a decision function profile. Let $[\mathbf{d}_i = d] = \{w \mid \mathbf{d}_i(w) = d\}.$

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(A1) Each agent knows her own decision:

$$[\mathbf{d}_i = d] \subseteq K_i([\mathbf{d}_i = d])$$

Comparing Knowledge

 $[j \succeq i]$: agent j is at least as knowledgeable as agent i.

$$[j \succeq i] := \bigcap_{E \in \wp(W)} (K_i(E) \Rightarrow K_j(E)) = \bigcap_{E \in \wp(W)} (\neg K_i(E) \cup K_j(E))$$

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 $[j \sim i] = [j \succeq i] \cap [i \succeq j]$

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Should I study or have a beer?

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There are three candidates, republican, independent and democrat. I will buy stock if the democrat looses and I will buy stock if the republican looses. Either the republican or democrat will loose. So, I should buy the stock.

R. Aumann, S. Hart and M. Perry. *Conditioning and the Sure-Thing Principle*. manuscript, 2005.

The Nixon Diamond

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Floating Conclusions



J. Horty. *Skepticism and floating conclusions*. Artificial Intelligence, 135, pp. 55 - 72, 2002.

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Interpersonal Sure-Thing Principle (ISTP)

For any pair of agents i and j and decision d,

$$K_i([j \succeq i] \cap [\mathbf{d}_j = d]) \subseteq [\mathbf{d}_i = d]$$

Interpersonal Sure-Thing Principle (ISTP): Illustration

Suppose that Alice and Bob, two detectives who graduated the same police academy, are assigned to investigate a murder case.
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However, Alice, single and a workaholic, continues to collect more information every day until the wee hours of the morning information which she does not necessarily share with Bob. Obviously, Bob knows that Alice is at least as knowledgeable as he is. Suppose that he also knows what Alices decision is. Since Alice uses the same investigation method as Bob, he knows that had he been in possession of the more extensive knowledge that Alice has collected, he would have made the same decision as she did. Thus, this is indeed his decision.

Implications of ISTP

Proposition. If the decision function profile **d** satisfies ISTP, then

$$[i \sim j] \subseteq \bigcup_{d \in D} ([\mathbf{d}_i = d] \cap [\mathbf{d}_j = d])$$

ISTP Expandability

Agent *i* is an **epistemic dummy** if it is always the case that all the agents are at least as knowledgeable as *i*. That is, for each agent *j*,

 $[j \succeq i] = W$

A decision function profile **d** on $\langle W, \Pi_1, \ldots, \Pi_n \rangle$ is **ISTP expandable** if for any expanded structure $\langle W, \Pi_1, \ldots, \Pi_{n+1} \rangle$ where n + 1 is an epistemic dummy, there exists a decision function \mathbf{d}_{n+1} such that $(\mathbf{d}_1, \mathbf{d}_2, \ldots, \mathbf{d}_{n+1})$ satisfies ISTP.

Suppose that after making their decisions, Alice and Bob are told that another detective, one E.P. Dummy, who graduated the very same police academy, had also been assigned to investigate the same case.

Suppose that after making their decisions, Alice and Bob are told that another detective, one E.P. Dummy, who graduated the very same police academy, had also been assigned to investigate the same case. In principle, they would need to review their decisions in light of the third detectives knowledge: knowing what they know about the third detective, his usual sources of information, for example, may impinge upon their decision.

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Generalized Agreement Theorem

If **d** is an ISTP expandable decision function profile on a partition structure $\langle W, \Pi_1, \ldots, \Pi_n \rangle$, then for any decisions d_1, \ldots, d_n which are not identical, $C(\bigcap_i [\mathbf{d}_i = d_i]) = \emptyset$.

Robert Aumann. Agreeing to Disagree. Annals of Statistics 4 (1976).

Theorem. Suppose that *n* agents share a common prior and have different private information. If there is common knowledge in the group of the posterior probabilities, then the posteriors must be equal.



They agree the true state is one of seven different states.



They agree on a common prior.



They agree that Experiment 1 would produce the blue partition.



They agree that Experiment 1 would produce the blue partition and Experiment 2 the red partition.



They are interested in the truth of $E = \{w_2, w_3, w_5, w_6\}$.



So, they agree that
$$P(E) = \frac{24}{32}$$
.



Also, that if the true state is w_1 , then Experiment 1 will yield $P(E|I) = \frac{P(E \cap I)}{P(I)} = \frac{12}{14}$



Suppose the true state is w_7 and the agents preform the experiments.



Suppose the true state is w_7 , then $Pr_1(E) = \frac{12}{14}$



Then $Pr_1(E) = \frac{12}{14}$ and $Pr_2(E) = \frac{15}{21}$



Suppose they exchange emails with the new subjective probabilities: $Pr_1(E) = \frac{12}{14}$ and $Pr_2(E) = \frac{15}{21}$



Agent 2 learns that w_4 is **NOT** the true state (same for Agent 1).



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Agent 1 learns that w_5 is **NOT** the true state (same for Agent 1).



The new probabilities are $Pr_1(E|I') = \frac{7}{9}$ and $Pr_2(E|I') = \frac{15}{17}$



After exchanging this information $(Pr_1(E|I') = \frac{7}{9} \text{ and } Pr_2(E|I') = \frac{15}{17})$, Agent 2 learns that w_3 is **NOT** the true state.

 $\frac{2}{32} \bullet_{W_1}$



No more revisions are possible and the agents agree on the posterior probabilities.

Models of Hard and Soft Information



$$\mathcal{M} = \langle W, \{\Pi_i\}_{i \in \mathcal{A}} \rangle$$

$$\Pi_i \text{ is agent } i'\text{s partition with } \Pi_i(w) \text{ the partition cell containing } w.$$

$$K_i(E) = \{w \mid \Pi_i(w) \subseteq E\}$$

Models of Hard and Soft Information



$$\mathcal{M} = \langle W, \{ \Pi_i \}_{i \in \mathcal{A}}, \{ p_i \}_{i \in \mathcal{A}}
angle$$

for each *i*, $p_i : W \to [0, 1]$ is a probability measure

$$B^{p}(E) = \{w \mid p_{i}(E \mid \Pi_{i}(w)) = \frac{\pi_{i}(E \cap \Pi_{i}(w))}{p_{i}(\Pi_{i}(w))} \geq p\}$$
1.
$$B_i^p(B_i^p(E)) = B_i^p(E)$$

2. If
$$E \subseteq F$$
 then $B_i^p(E) \subseteq B_i^p(F)$

3. $\pi(E \mid B_i^p(E)) \geq p$

Common *p*-belief

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"We show that the weaker concept of "common belief" can function successfully as a substitute for common knowledge in the theory of equilibrium of Bayesian games."

D. Monderer and D. Samet. *Approximating Common Knowledge with Common Beliefs*. Games and Economic Behavior (1989).

Common *p*-belief: definition

$$B_i^p(E) = \{w \mid p(E \mid R_i(w)) \ge p\}$$

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Common *p*-belief: definition

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An event *E* is **evident** *p***-belief** if for each $i \in A$, $E \subseteq B_i^p(E)$

An event *F* is **common** *p***-belief** at *w* if there exists and evident *p*-belief event *E* such that $w \in E$ and for all $i \in A$, $E \subseteq B_i^p(F)$



Two agents either hear (H) or don't hear (D) the announcement.





The probability that an agent hears is $1 - \epsilon$.



The agents know their "type".



The event "everyone hears" $(E = \{w_1\})$



The event "everyone hears" $(E = \{w_1\})$ is **not** common knowledge



The event "everyone hears" $(E = \{w_1\})$ is **not** common knowledge, but it is common $(1 - \epsilon)$ -belief



The event "everyone hears" $(E = \{w_1\})$ is **not** common knowledge, but it is common $(1 - \epsilon)$ -belief: $B_i^{(1-\epsilon)}(E) = \{w \mid p(E \mid \Pi_i(w)) \ge 1 - \epsilon\} = \{w_1\} = E$, for i = 1, 2 **Theorem**. If the posteriors of an event X are common p-belief at some state w, then any two posteriors can differ by at most 1 - p.

D. Samet and D. Monderer. *Approximating Common Knowledge with Common Beliefs*. Games and Economic Behavior, Vol. 1, No. 2, 1989.