

# CMSC 132: Object-Oriented Programming II

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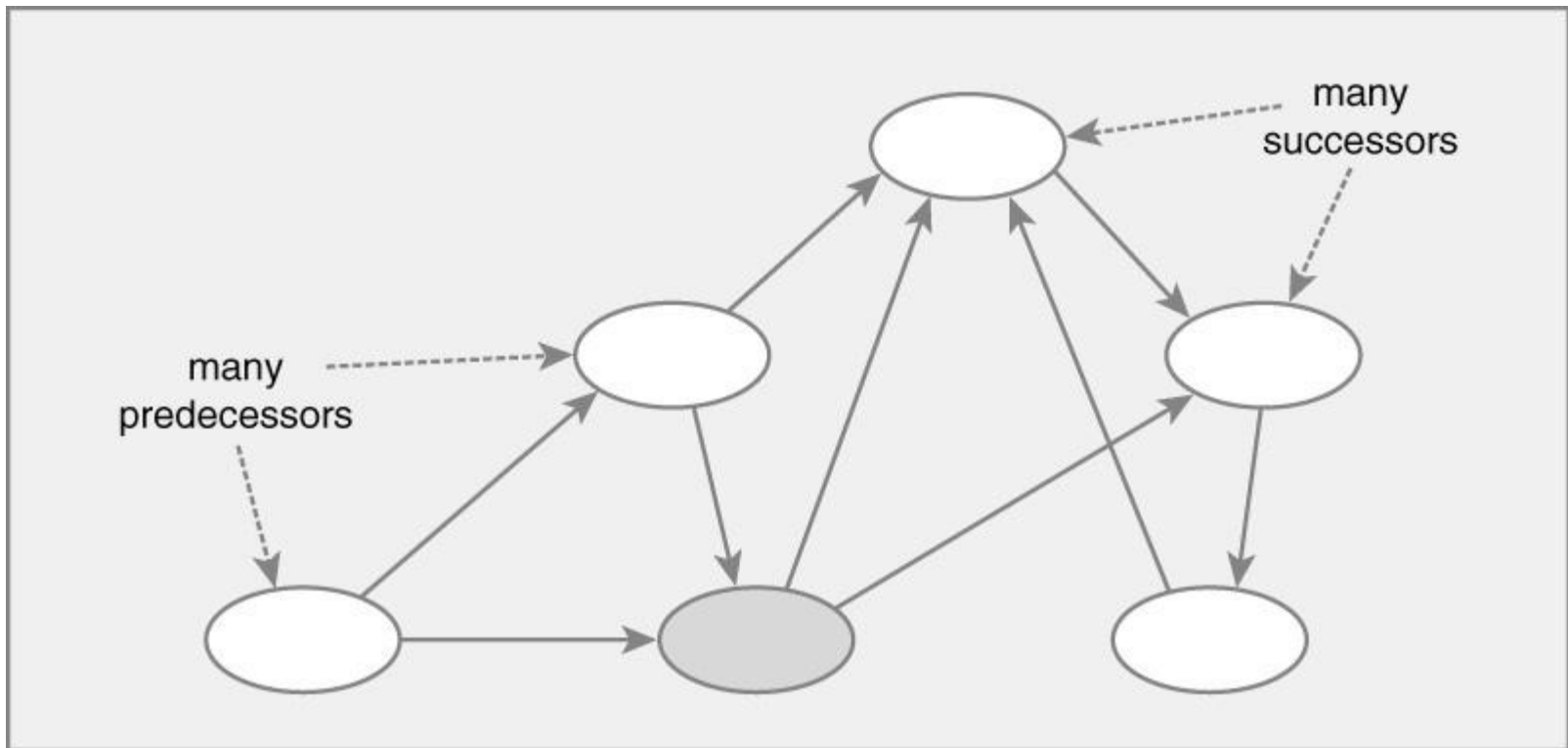


## **Graphs & Graph Traversal**

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# Graph Data Structures

- **Many-to-many relationship between elements**
  - Each element has **multiple** predecessors
  - Each element has **multiple** successors



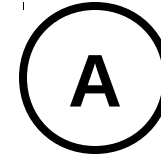
# Graph Definitions

## ■ Node

- Element of graph

- State

- List of adjacent/neighbor/successor nodes



## ■ Edge

- Connection between two nodes

- State

- Endpoints of edge



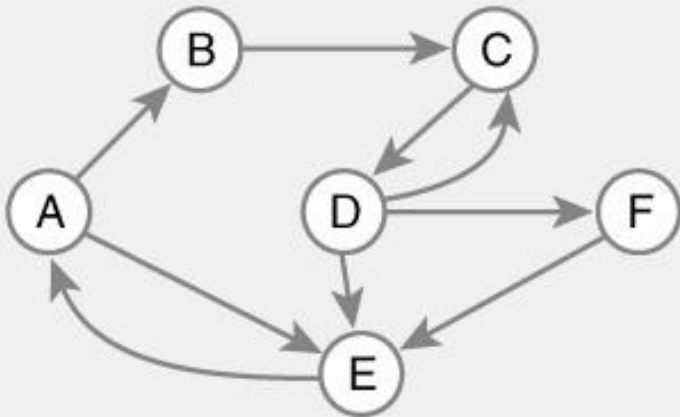
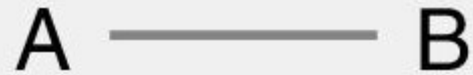
# Graph Definitions

## ■ Directed graph

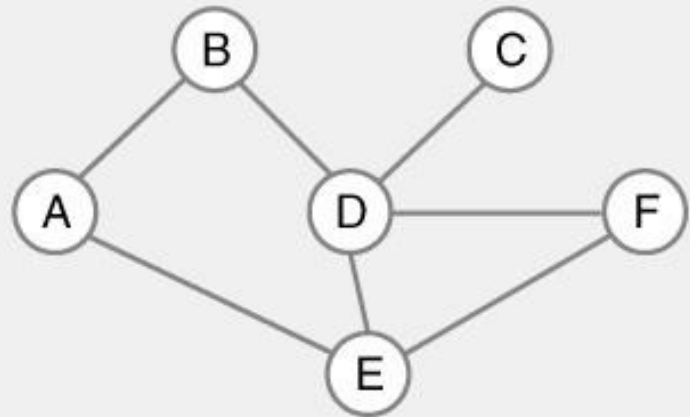
■ Directed edges

## ■ Undirected graph

■ Undirected edges



(a) Directed graph

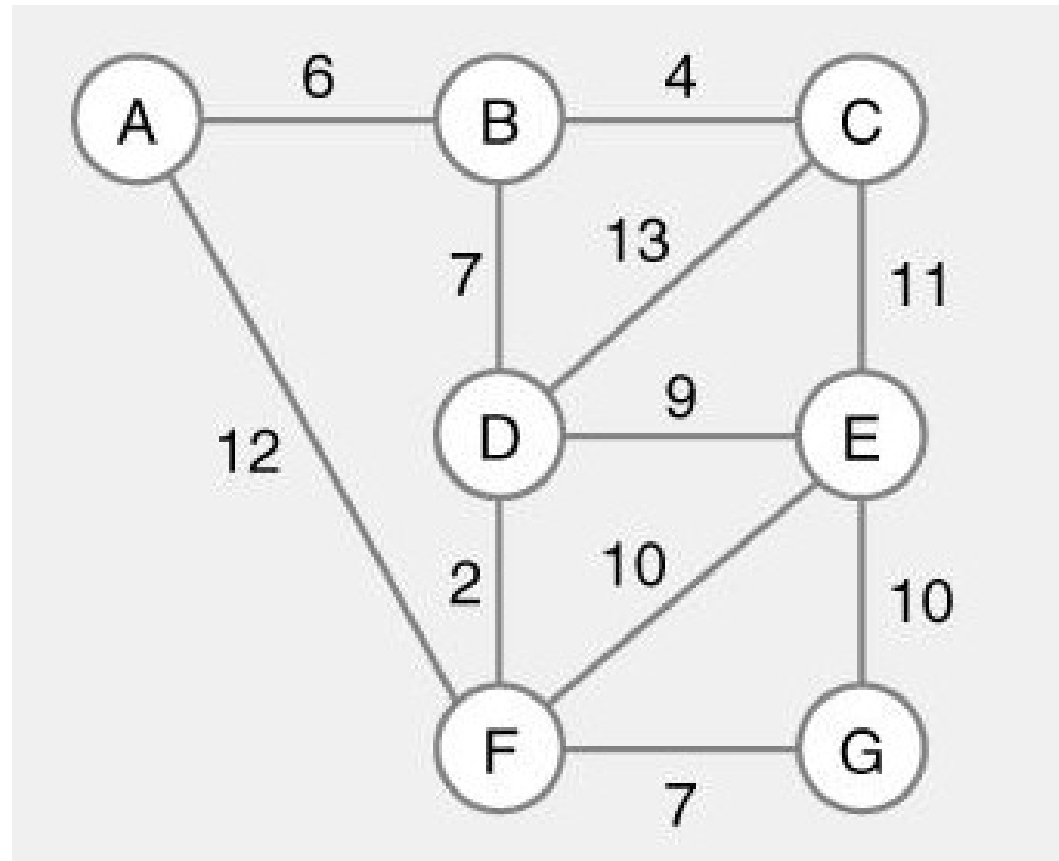


(b) Undirected graph

# Graph Definitions

## ■ Weighted graph

■ Weight (cost) associated with each edge



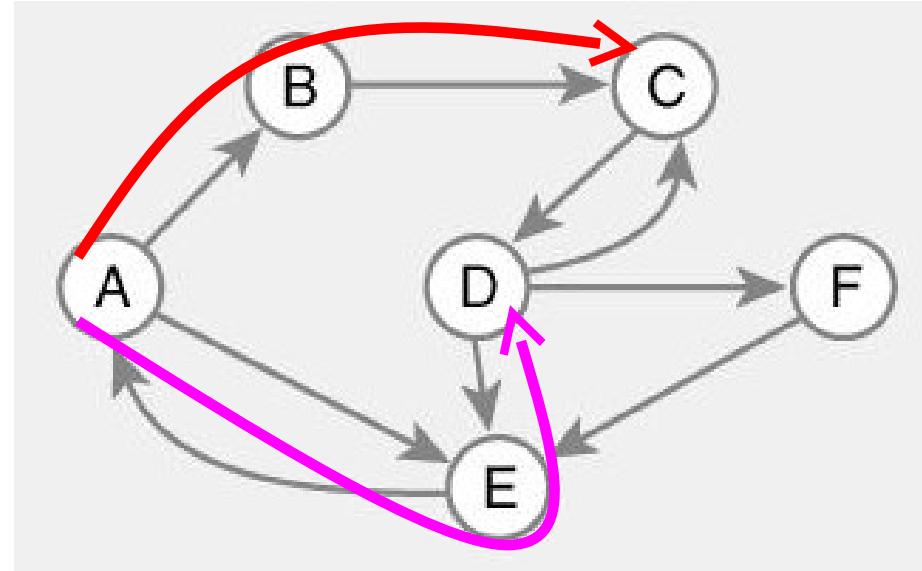
# Graph Definitions

## ■ Path

- Sequence of nodes  $n_1, n_2, \dots, n_k$
- Edge exists between each pair of nodes  $n_i, n_{i+1}$

## ■ Example

- A, B, C is a path
- A, E, D is not a path



# Graph Definitions

## ■ Cycle

- Path that ends back at starting node

- Example

  - A, E, A

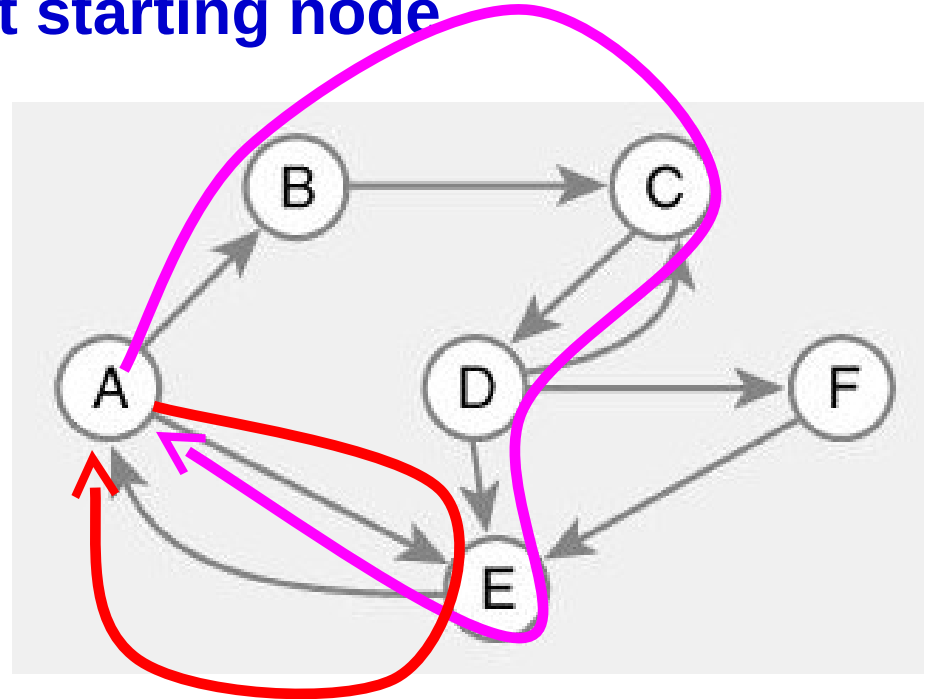
  - A, B, C, D, E, A

## ■ Simple path

- No cycles in path

## ■ Acyclic graph

- No cycles in graph



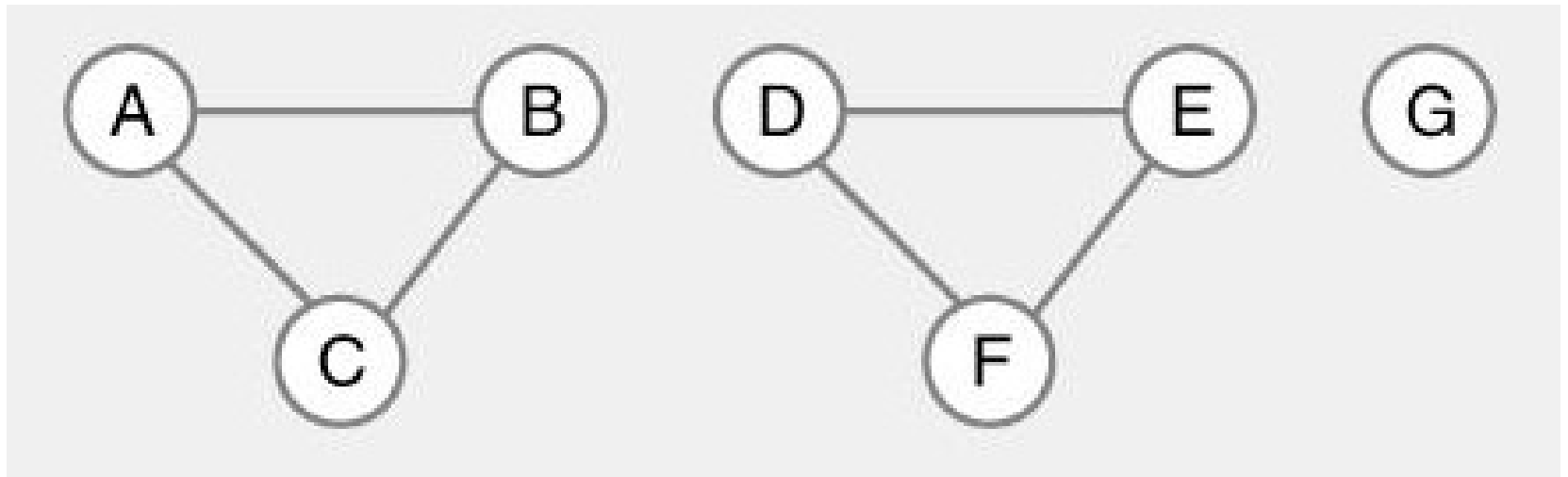
# Graph Definitions

## ■ Reachable

- Path exists between nodes

## ■ Connected graph

- Every node is reachable from some node in graph



**Unconnected graphs**



# Graph Operations

## ■ Traversal (search)

- Visit each node in graph exactly once
- Usually perform computation at each node
- Two approaches
  - Breadth first search (BFS)
  - Depth first search (DFS)

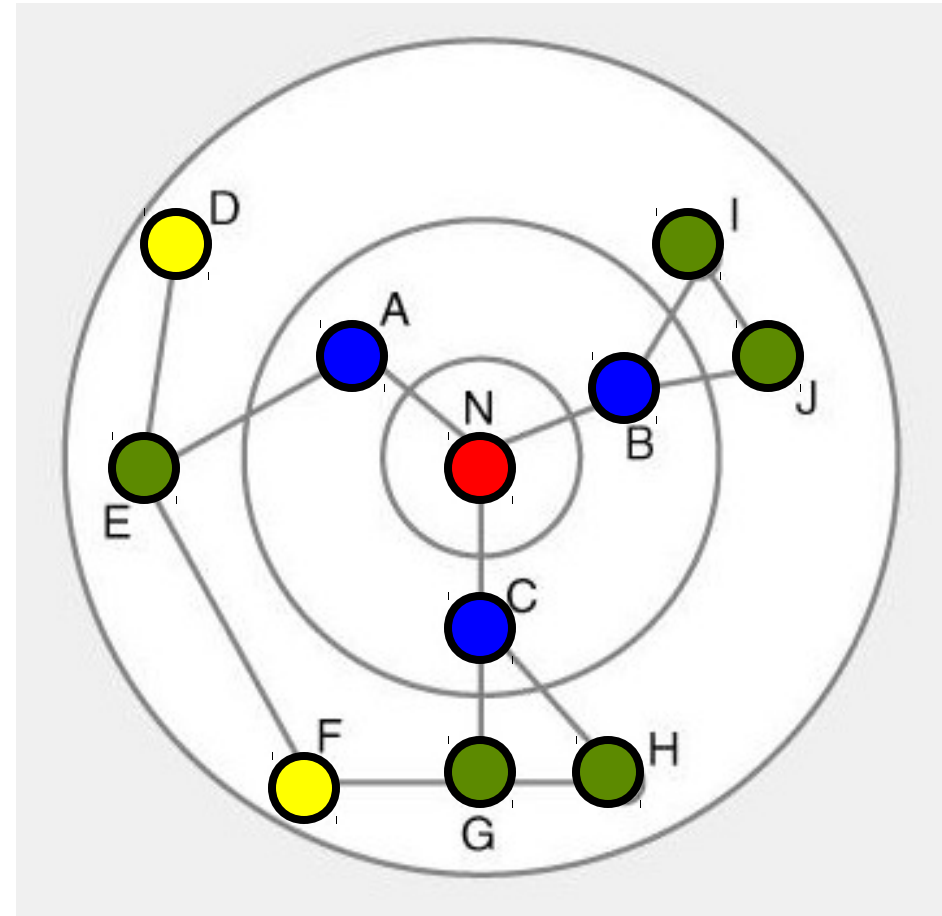
# Breadth-first Search (BFS)

## ■ Approach

- Visit all neighbors of node first
- View as series of expanding circles
- Keep list of nodes to visit in queue

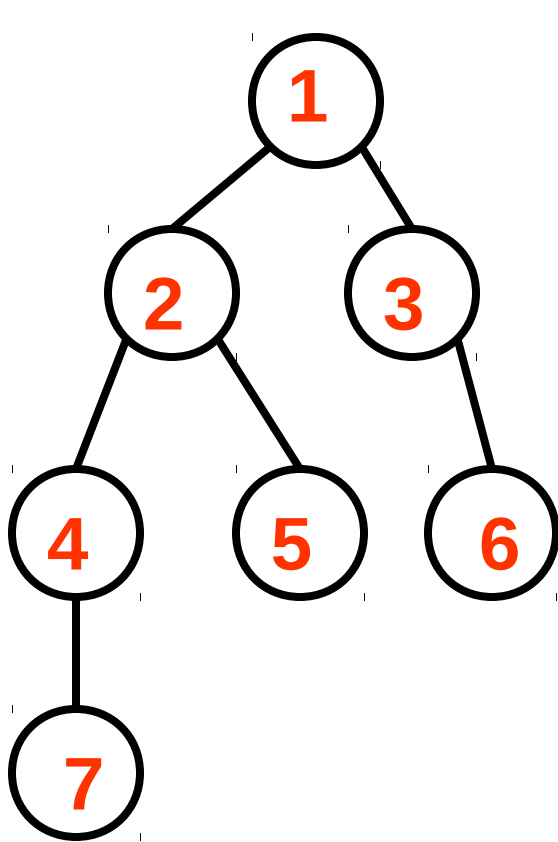
## ■ Example traversal

1. n
2. a, c, b
3. e, g, h, i, j
4. d, f

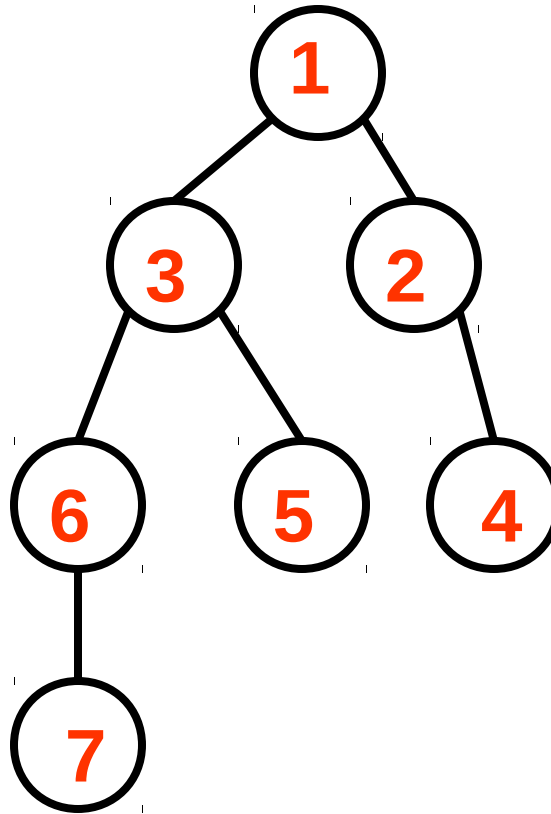


# Breadth-first Tree Traversal

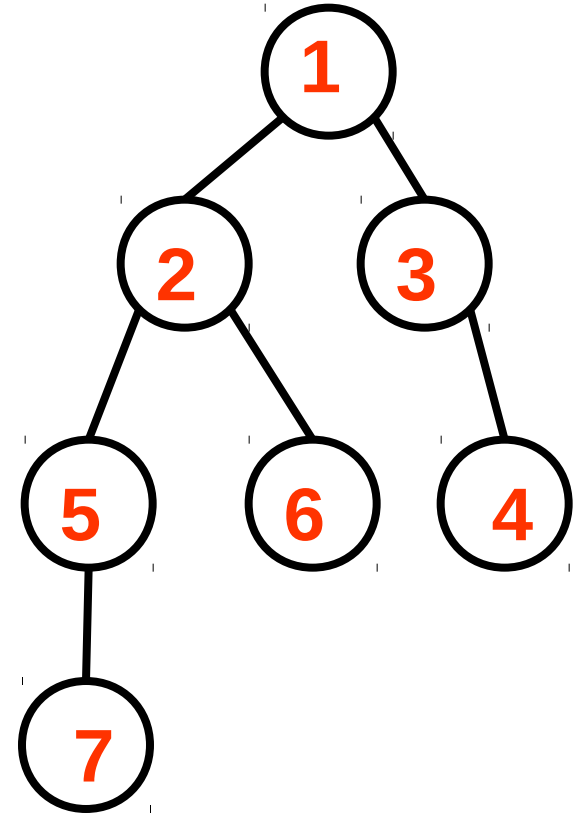
## ■ Example traversals starting from 1



Left to right



Right to left



Random

# Traversals Orders

## ■ Order of successors

### ■ For tree

- Can order children nodes from left to right

### ■ For graph

- Left to right doesn't make much sense
- Each node just has a set of successors and predecessors; there is no order among edges

## ■ For breadth first search

- Visit all nodes at distance  $k$  from starting point
- Before visiting any nodes at (minimum) distance  $k+1$  from starting point

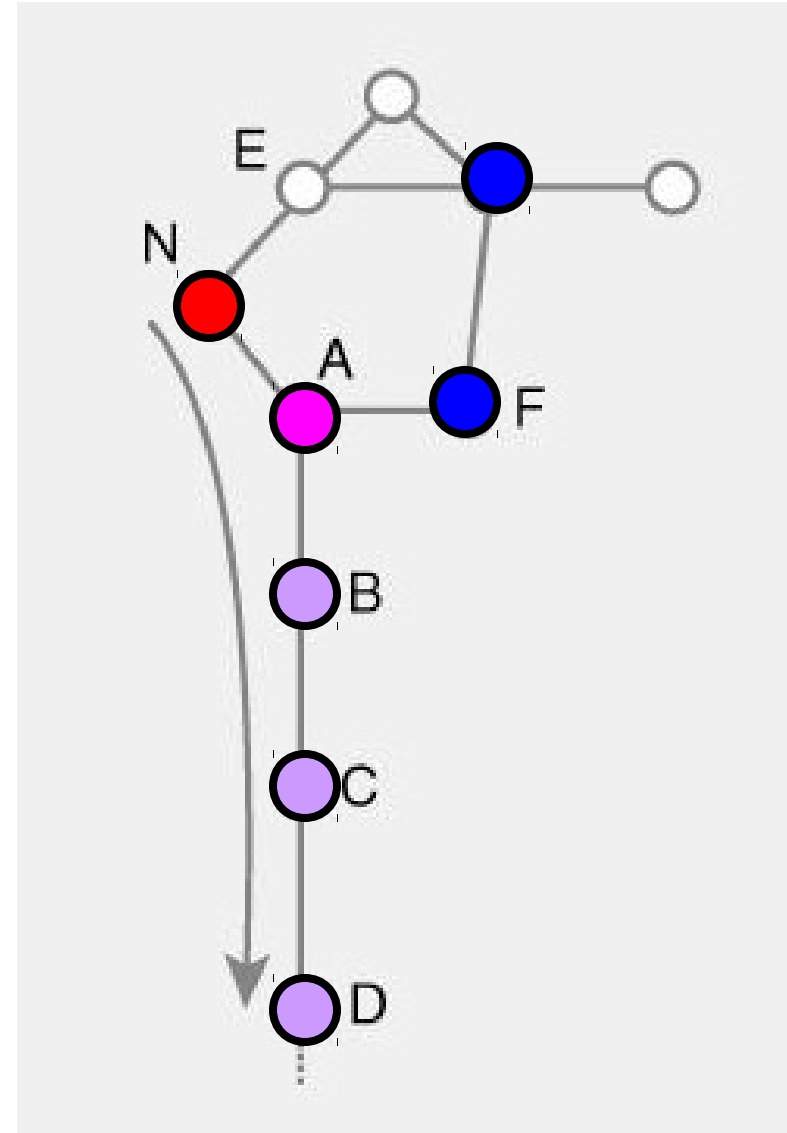
# Depth-first Search (DFS)

## ■ Approach

- Visit all nodes on path first
- **Backtrack** when path ends
- Keep list of nodes to visit in a stack

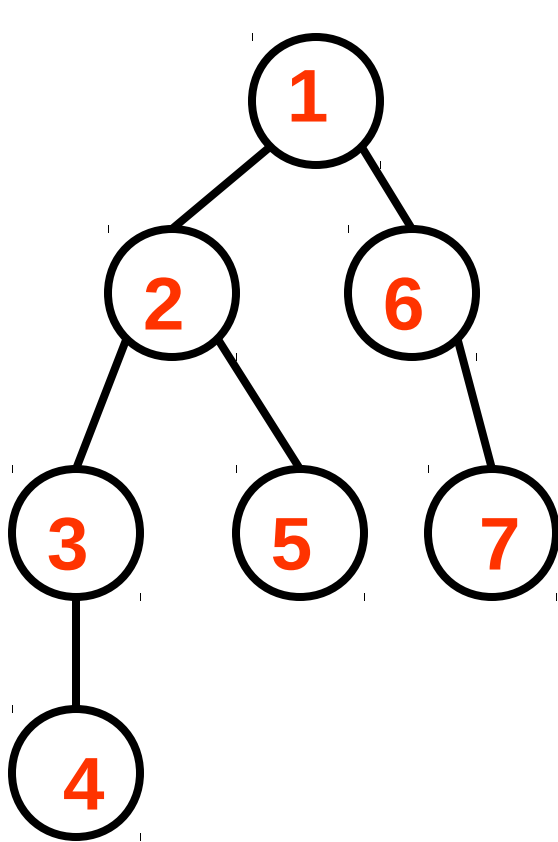
## ■ Example traversal

1. **N**
2. **A**
3. **B, C, D, ...**
4. **F...**

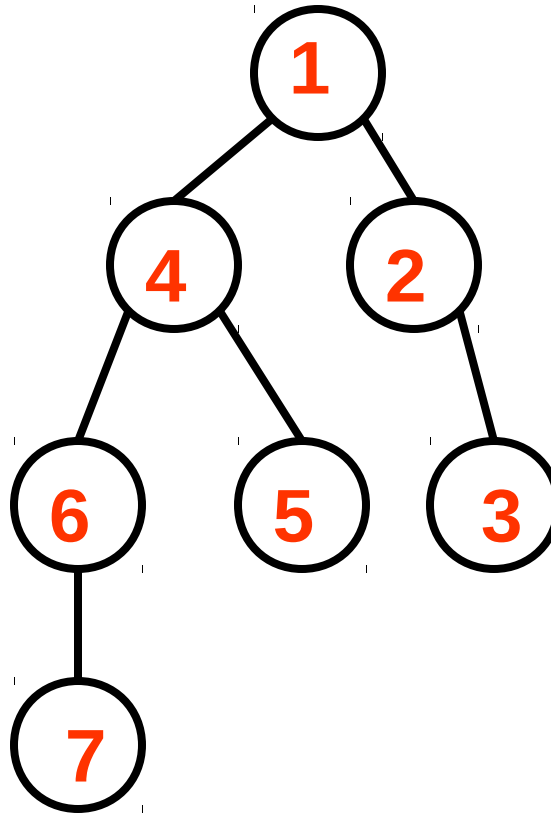


# Depth-first Tree Traversal

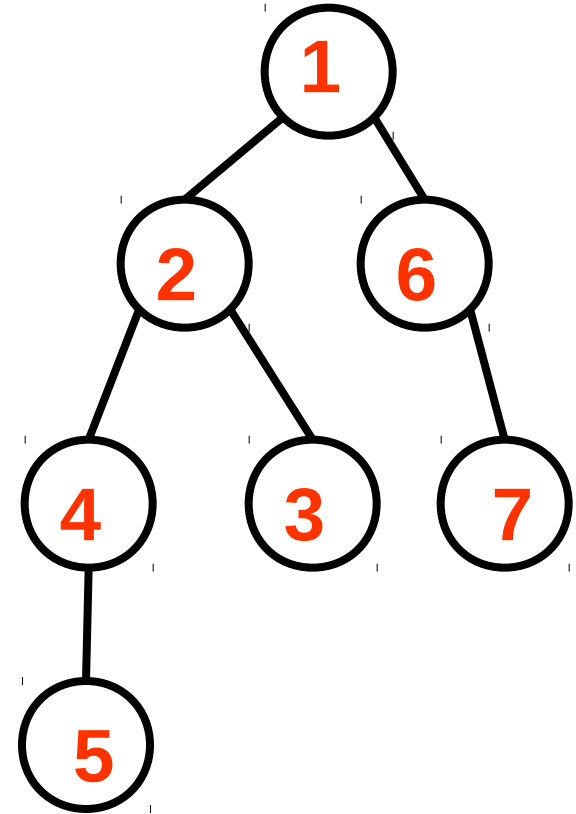
## ■ Example traversals from 1 (preorder)



Left to right



Right to left



Random

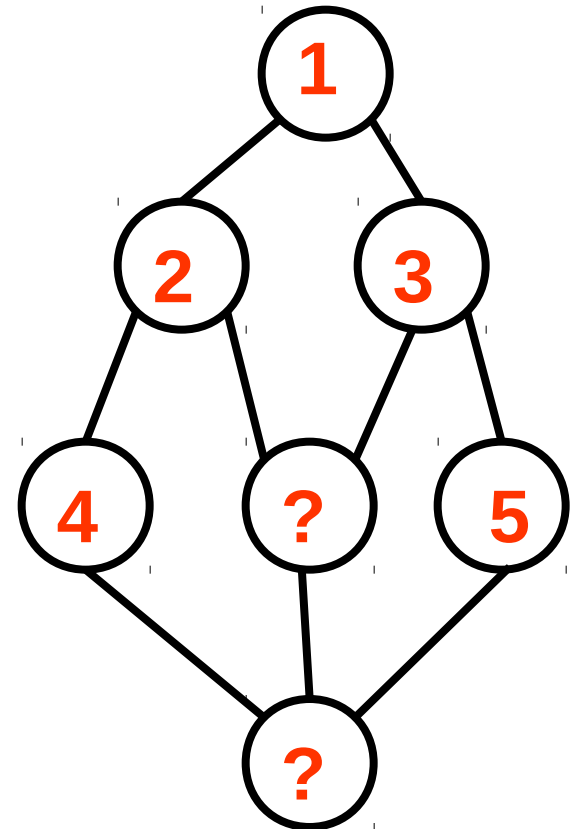
# Traversal Algorithms

## ■ Issue

- How to avoid revisiting nodes
- Infinite loop if cycles present

## ■ Approaches

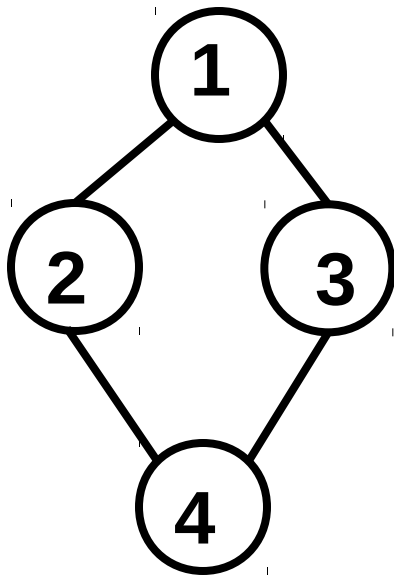
- Record set of visited nodes
- Mark nodes as visited



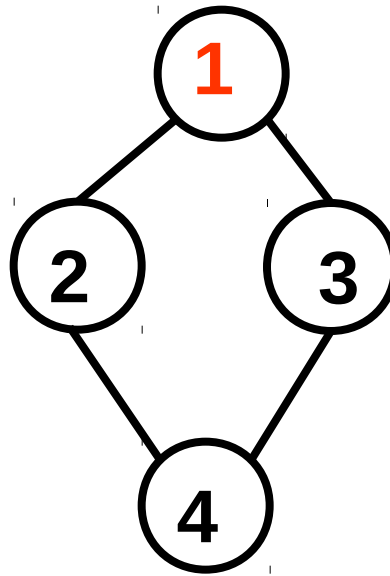
# Traversal – Avoid Revisiting Nodes

## ■ Record set of visited nodes

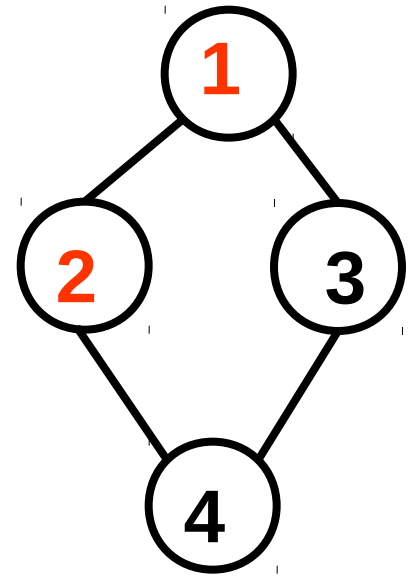
- Initialize { Visited } to empty set
- Add to { Visited } as nodes is visited
- Skip nodes already in { Visited }



$V = \emptyset$



$V = \{ 1 \}$

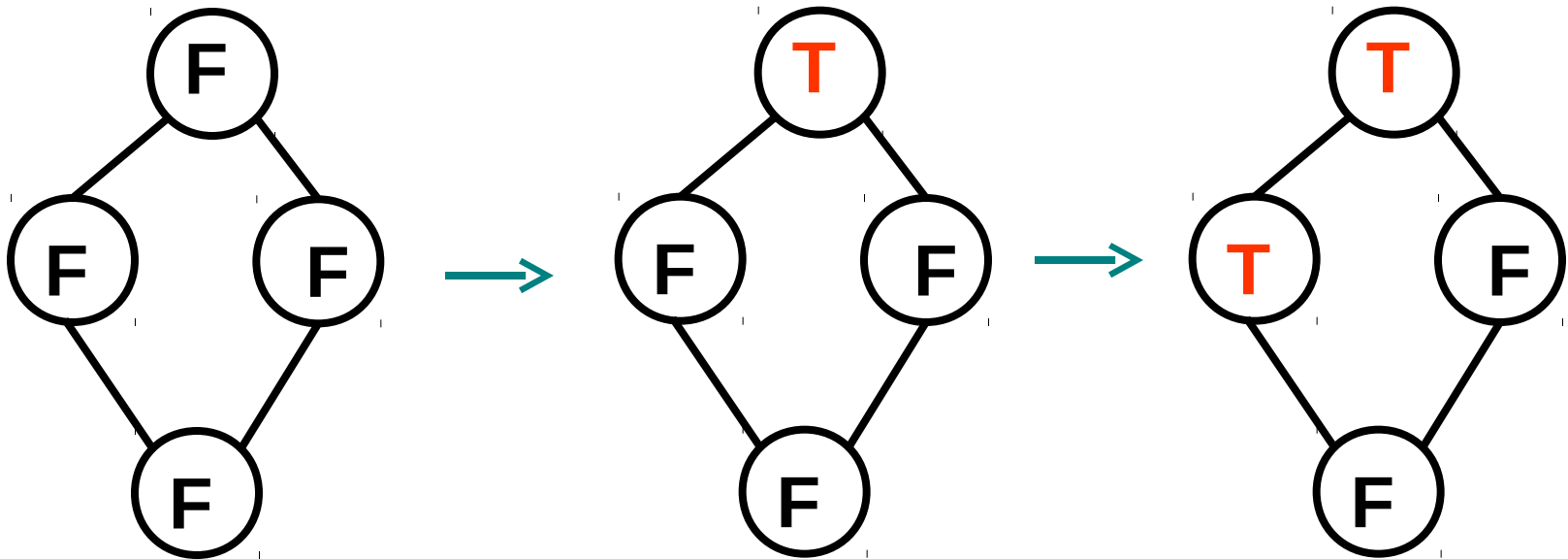


$V = \{ 1, 2 \}$



# Traversal – Avoid Revisiting Nodes

- **Mark nodes as visited**
  - Initialize tag on all nodes (to False)
  - Set tag (to True) as node is visited
  - Skip nodes with tag = True



# General Traversal Algorithm

**{ Visited } =  $\emptyset$**

**{ Discovered } = { 1st node }**

**while ( { Discovered }  $\neq \emptyset$  )**

**take node X out of { Discovered }**

**if X not in { Visited }**

**add X to { Visited }**

**for each successor Y of X**

**if ( Y is not in { Visited } )**

**add Y to { Discovered }**

# Traversal Algorithm Using Tags

for all nodes X

set X.tag = False

{ Discovered } = { 1st node }

while ( { Discovered }  $\neq \emptyset$  )

take node X out of { Discovered }

if (X.tag = False)

set X.tag = True

for each successor Y of X

if (Y.tag = False)

add Y to { Discovered }

# Traversal Algorithm with Queue

for all nodes X

**X.tag = False**

put 1<sup>st</sup> node in Queue

while ( Queue not empty )

**take node X out of Queue**

**if (X.tag = False)**

**set X.tag = True**

**for each successor Y of X**

**if (Y.tag = False)**

**put Y in Queue**

# Traversal Algorithm with Stack

for all nodes X

**X.tag = False**

put 1<sup>st</sup> node in Stack

while (Stack not empty )

**pop X off Stack**

**if (X.tag = False)**

**set X.tag = True**

**for each successor Y of X**

**if (Y.tag = False)**

**push Y onto Stack**

# BFS vs. DFS Traversal

- **Implement { Discovered } as Queue**
  - First in, first out
  - Traverse nodes breadth first
- **Implement { Discovered } as Stack**
  - First in, last out
  - Traverse nodes depth first

# Recursive Traversal Algorithm

**Traverse( )**

**for all nodes X**

**set X.tag = False**

**Visit ( 1<sup>st</sup> node )**

**Visit ( X )**

**set X.tag = True**

**for each successor Y of X**

**if (Y.tag = False)**

**Visit ( Y )**

# Recursive Graph Traversal

- **Can traverse graph using recursive algorithm**
  - **Recursively visit successors**
- **Implicit call stack & backtracking**
  - **Results in depth-first traversal**